## **NASA GRIP Aircraft**



# NASA DC-8





## **DC-8 Communications**



# **REVEAL - Research Environment for Vehicle-Embedded Analysis on Linux**

- Real-time aircraft position and data plotted on Google Earth
- X-Chat capability with science team members

#### **Instrument Inter-communications**

- Gigabit ethernet data system
- High Res. LCD displays

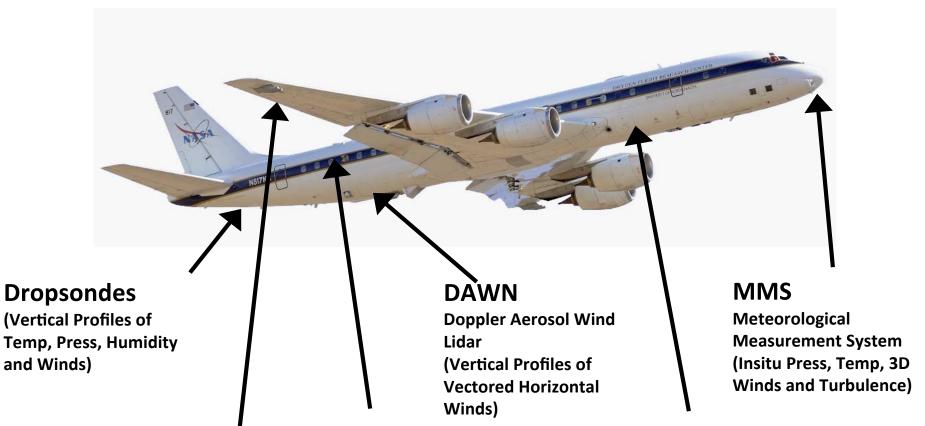
### **IRIDIUM and INMARSAT Satcom**

- 9600 bps IRIDIUM
- 432kbps INMARSAT

## Digital forward and Nadir video system

## **GRIP DC-8 Payload**





CAPS, CVI, PIP

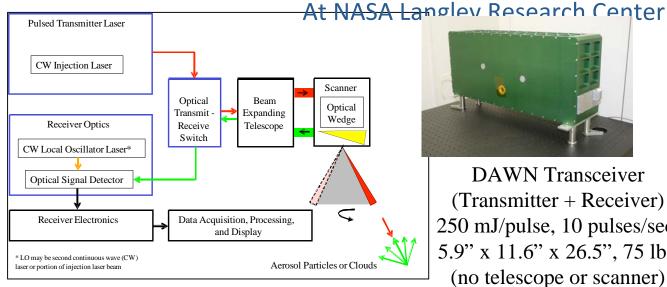
(Cloud Particle Size distributions, Precip Rate, Rain & Ice water content)

**LASE** 

Lidar Atmospheric Sensing Experiment (H2Ov, Aerosol profiles and Cloud distributions) APR-2

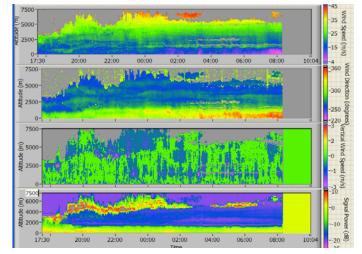
Airborne Precipitation Radar Dual Frequency (Vertical Structure Rain Reflectivity and Cross Winds)

## Pulsed 2-Micron Coherent-Detection Doppler Wind Profiling Lidar **System**



**DAWN** Transceiver (Transmitter + Receiver) 250 mJ/pulse, 10 pulses/sec. 5.9" x 11.6" x 26.5", 75 lbs. (no telescope or scanner)

#### Elements of Coherent (Heterodyne) Doppler Lidar



March 11-12, 2009, unattended autonomous operation, ~ 14 hrs, 3minute shot integration times, 5 Hz Tilted Beam - 45 deg elev. 2 Azimuths Horiz. Wind Speed 4 - 45 m/s

Horizontal Wind Direction  $220 - 360 \deg$ 

Vertical Wind Speed -3 - +3 m/s

Vertical Signal Power ~ 35 dB

#### Predicted DC-8 Performance

- Horizontal vector wind profile from 300 m below DC-8 to ground, thick clouds permitting, ~ 3 min. integration
- Line-of-sight velocity precision better than 1 m/s
- Line-of-sight velocity bias less than 0.1 m/s
- Deliver LOS and/or horizontal wind profiles
- Multiple integration times permitted on same data
- Multiple vertical resolutions permitted on same data
- On board real-time displays
- Archive all data

# NASA Global Hawk 10/23/09





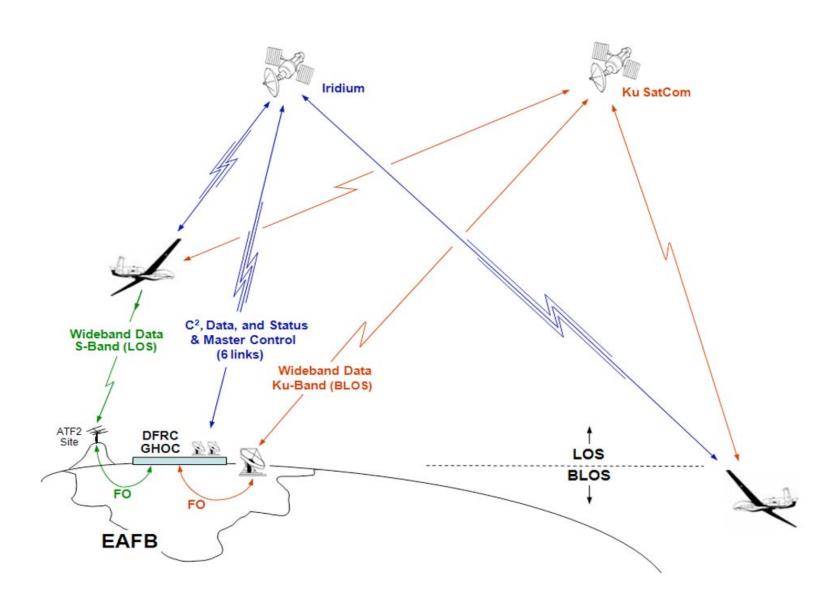
# **GHOC Flight Operations Room**





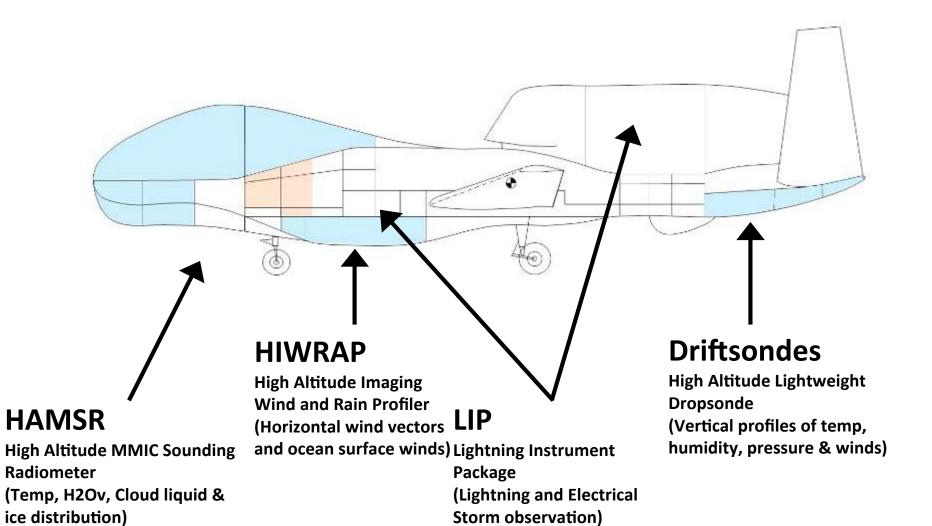
# **GH UAS Communications**





# **GRIP GH Payload**







## HAMSR Microwave Sounder on Global Hawk

Bjorn Lambrigtsen, Shannon Brown - JPL

#### Thermodynamic structure

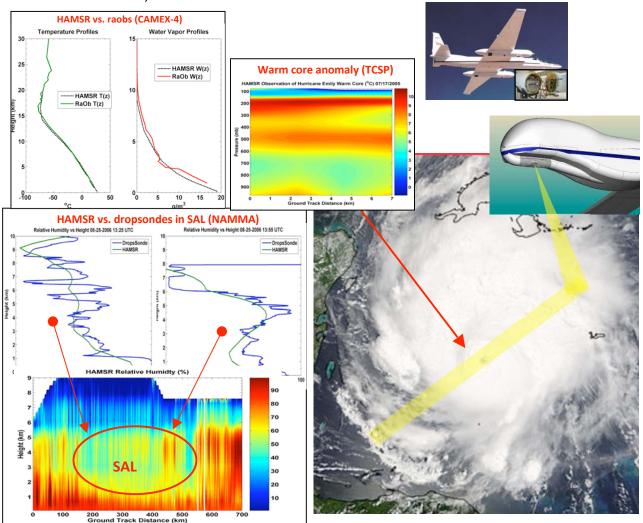
- T(z), q(z), L(z) clear & cloudy
- Rain rate, IWP (experimental)
- 1 km V x 2 km H in 40-km swath
- 25 channels: 50, 118 and 183 GHz

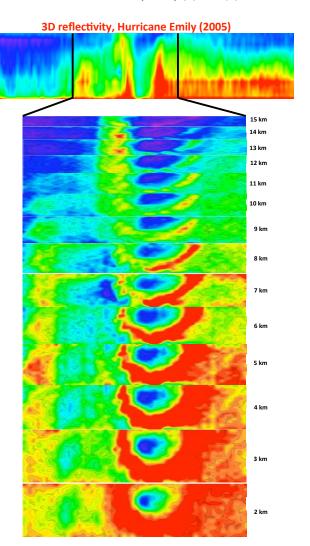
#### Multiple platforms

- ER-2 (CAMEX-4, TCSP)
- DC-8 (NAMMA)
- Global Hawk (ready late 2009)

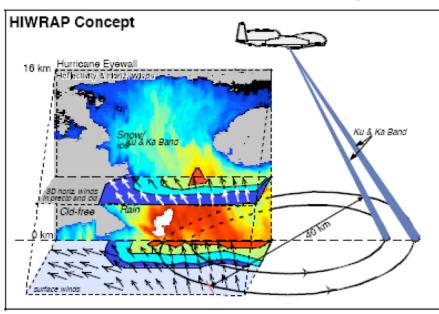
#### **Convective structure**

- Radar-like reflectivity
- 1 km vert.res/40 km swath
- Conv.intens., precip(z), ice(z)





# High-Altitude Imaging Wind and Rain Profiler (HIWRAP)



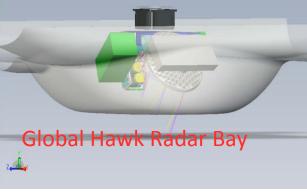
## NASA Technology Development

- Low power solid-state transmitter and pulse-compression
- ➤ Single aperture antenna for two beams (incidence 30°, 40°) and two frequencies (14, 35 GHz), conical scan
- High altitude, power efficient real-time FPGA-based digital receiver and processor
- > GPM frequencies

\*3D winds (grid point retrieval) and reflectivity
\*Ocean scatterometry (QuikScat-like measurements)



WB-57





## **Pre-GRIP**



## April/May 2010

• Two test flights; 1 local in DFRC range and 1 24hr flight.

# Test of Certificate of Authorization (COA) and Flight Information Regions (FIR) Process

• GH flight to the Gulf of Mexico, possibly Atlantic

### Instruments on board

- HAMSR
- HIWRAP
- GH Wx Instruments
- LIP?

## **GH UAS Wx Hazard Mods**



### **Install HD Camera in Aircraft Nose**

Low-Light / Visual / IR

#### **Install Wx Severe Storm Instruments**

- Storm-scope for lightening detection
- Data Link NexRad?

## **Install Turbulence Package**

Turbulence Sensor w/ Display

# **GRIP DC-8 Range from FLL**





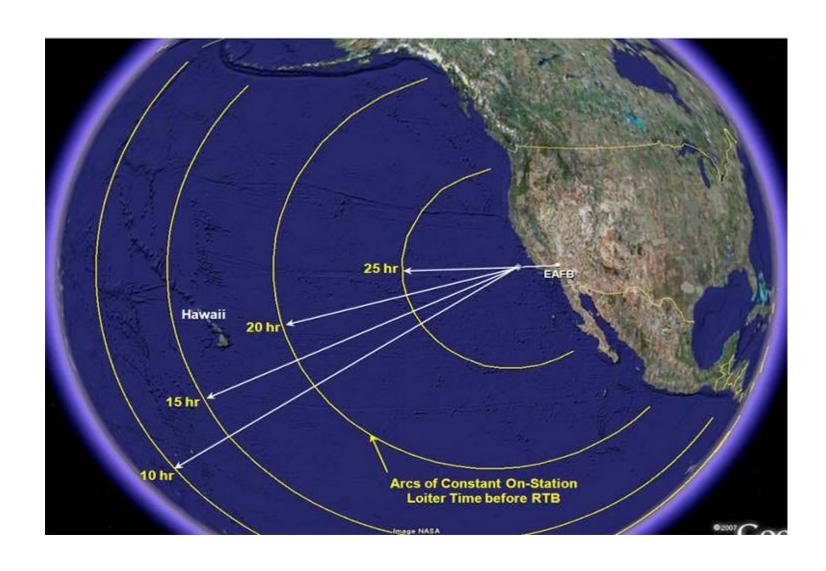
# **Loiter Capability from DFRC**





# **East Pac Loiter Capability**





## **GRIP Aircraft Platforms**

**Questions?** 

# **DC-8 Interior**



